

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	45600	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4 or packag\$4)same(mov\$6 or tranv\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L2	14709	1 same(ly\$4 or sid\$3 or rest\$4 or fall\$4 or collaps4 or drop\$4 or down\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:53
L3	5327	2 same(return\$4 or reject\$3 or remov\$4 or reinsert\$3 or push\$3 or redirect\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56
L4	1815	3 same(bottom\$2 or mouth\$3 or top\$2)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56
L5	2070	3 same(bottom\$2 or mouth\$3 or top\$2 or inlet\$3 or outlet\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L6	23	5 same(video\$2)	US-PGPUB; USPAT	OR	ON	2006/05/24 13:09
L7	177	5 same(empty\$3)	US-PGPUB; USPAT	OR	ON	2006/05/24 11:36
L8	469	5 same(empty\$3 or hollow\$2 or vac\$6)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L9	62	8 same(user\$2 or person\$3 or viewer\$4 or operator\$3 or human\$3)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:58
L10	29781	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4)same(mov\$6 or tranv\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L11	29783	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4)same(mov\$6 or tranf\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L12	30475	(detect\$4 or scan\$4 or captur\$4 or read\$4 or sensor\$3)same(container\$4 or bottl\$4)same(mov\$6 or transf\$6 or transfer\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:52
L13	10410	12 same(ly\$4 or sid\$3 or rest\$4 or fall\$4 or collaps4 or drop\$4 or down\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:53
L14	3955	13 same(return\$4 or reject\$3 or remov\$4 or reinsert\$3 or push\$3 or redirect\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56

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L15	1377	14 same(bottom\$2 or mouth\$3 or top\$2)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:56
L16	1377	15 same(bottom\$2 or mouth\$3 or top\$2 or inlet\$3 or outlet\$4)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L17	281	16 same(empty\$3 or hollow\$2 or vac\$6)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:57
L18	43	17 same(user\$2 or person\$3 or viewer\$4 or operator\$3 or human\$3)	US-PGPUB; USPAT	OR	ON	2006/05/24 12:58
L19	1	"5603363".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:07
L20	1	"5299715".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L21	1	"4886190".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L22	1	"4850387".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L23	1	"5794519".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L24	1	"5773067".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:08
L25	1	"5603254".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:09
L26	1	"5501525".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:09
L27	1	"5692029".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:14
L28	1	"5675516".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:14
L29	1	"5675516".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:14
L30	1	"5443164".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L31	1	"5443164".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L32	1	"5150307".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L33	1	"5150307".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:15
L34	1	"5007096".PN.	USPAT; USOCR	OR	ON	2006/05/24 13:16



Search Result - Print Format

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Key: IEEE JNL = IEEE Journal or Magazine, IEE JNL = IEE Journal or Magazine, IEEE CNF = IEEE Conference, IEE CNF = IEE Conference, IEEE STD = IEEE Standard

1. Pose detection of moving vehicle using rotating LSB (laser slit beam)

Sun Ho Kim; Kun Kook Park; Kyoung Taik Park; Jung Hwan Ahn;
Industrial Electronics, 2001. Proceedings. ISIE 2001. IEEE International Symposium on
Volume 1, 12-16 June 2001 Page(s):83 - 88 vol.1

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2. Remote bar-code localisation using mathematical morphology

Arnould, S.; Awcock, G.J.; Thomas, R.;
Image Processing and Its Applications, 1999. Seventh International Conference on (Conf. Publ. No. 465)
Volume 2, 13-15 July 1999 Page(s):642 - 646 vol.2

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3. Measurement of 3D spreader position for automatic landing system

Jung Jae Lee; Gi Gun Nam; Bong Ki Lee; Jang Myung Lee;
Industrial Electronics Society, 2004. IECON 2004. 30th Annual Conference of IEEE
Volume 3, 2-6 Nov. 2004 Page(s):3008 - 3013 Vol. 3

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4. Manipulation support system for large serving robots

Hildebrandt, A.; Sawodny, O.;
Control Applications, 2004. Proceedings of the 2004 IEEE International Conference on
Volume 2, 2-4 Sept. 2004 Page(s):934 - 938 Vol.2

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5. LOCO GPSI: Preserve the GPS advantage for defense and security

Simonsen, K.; Suycott, M.; Crumplar, R.; Wohlfeld, J.;
Position Location and Navigation Symposium, 2004. PLANS 2004
26-29 April 2004 Page(s):598 - 603

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6. Signal processing applied to the dolphin-based sonar system

Houser, D.; Martin, S.; Phillips, M.; Bauer, E.; Herrin, T.; Moore, P.;
OCEANS 2003. Proceedings
Volume 1, 2003 Page(s):297 - 303 Vol.1

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7. Parallel Lanczos bidiagonalization for total least squares filter in robot navigation

Yang, L.T.;
Parallel Computing in Electrical Engineering, 2002. PARELEC '02. Proceedings. International Conference on
22-25 Sept. 2002 Page(s):415 - 418

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8. CCD camera calibration for underwater laser scanning system

Wang, C.C.; Shyue, S.W.; Hsu, H.C.; Sue, J.S.; Huang, T.C.;
OCEANS, 2001. MTS/IEEE Conference and Exhibition
Volume 4, 5-8 Nov. 2001 Page(s):2511 - 2517 vol.4

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9. **Fast centroid estimation algorithm for high-rate detectors based on a two-point Gaussian fit**
Pietraski, P.J.; Zojceski, Z.;
Nuclear Science Symposium, 1999. Conference Record. 1999 IEEE
Volume 1, 24-30 Oct. 1999 Page(s):292 - 297 vol.1
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10. **Acoustical/optical technology integration with a manned submersible and a ROV for the investigation of a radioactive materials disposal site and a sewage diffuser outfall**
Lindsay, J.A.; Coles, B.; Babb, I.; Tomey, D.; Lieberman, M.; Nevis, A.; Taylor, J.S., Jr.; Askew, T., Jr.; Bell, W.J.; Kea K.; Louft, H.; Fredette, T.; Regan, R.;
Underwater Technology, 1998. Proceedings of the 1998 International Symposium on
15-17 April 1998 Page(s):395 - 400
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11. **The design of a radar-based navigation system for large outdoor vehicles**
Durrant-Whyte, H.; Bell, E.; Avery, P.;
Robotics and Automation, 1995. Proceedings., 1995 IEEE International Conference on
Volume 1, 21-27 May 1995 Page(s):764 - 769 vol.1
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12. **Environmental characterization with magnetics and STOLS**
Foley, J.E.;
Proceedings of the IEEE
Volume 82, Issue 12, Dec. 1994 Page(s):1823 - 1834
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13. **MDR for law enforcement [motion detector radar]**
Frazier, L.M.;
Potentials, IEEE
Volume 16, Issue 5, Dec 1997-Jan 1998 Page(s):23 - 26
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14. **Iterative reconstruction and statistical optimization for the nondestructive assay of distributed gamma sources in a large nuclear waste container**
Chin-Jen Chang; Anghaie, S.;
Nuclear Science, IEEE Transactions on
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15. **Fast centroid estimation algorithm for high-rate detectors based on a two-point Gaussian fit**
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16. **Exploring data rate limitations of channel front-ends for rigid disk drives**
Klaassen, K.B.; van Peppen;
Magnetics, IEEE Transactions on
Volume 37, Issue 2, March 2001 Page(s):619 - 626
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17. **LOCO GPSI: preserve the GPS advantage for defense and security**
Simonsen, K.; Suycott, M.; Crumplar, R.; Wohlfel, J.;
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Volume 19, Issue 12, Dec. 2004 Page(s):3 - 7
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18. **Model gantry crane with dynamic feedback swing control**
Benn, L.; Burton, B.; Ireland, J.; Sen Wang; Harley, R.;
Industrial Electronics, 2004 IEEE International Symposium on
Volume 1, 4-7 May 2004 Page(s):265 - 269 vol. 1
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19. **A Scalable Multi-Replication Framework for Data Grid**
Takizawa, S.; Takamiya, Y.; Nakada, H.; Matsuoka, S.;
Applications and the Internet Workshops, 2005. Saint Workshops 2005. The 2005 Symposium on
31-04 Jan. 2005 Page(s):310 - 315
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20. **A Modular Approach to Real-Time Cork Classification Using Image Processing**
Lima, J.L.; Costa, P.G.;
Emerging Technologies and Factory Automation, 2005. ETFA 2005. 10th IEEE Conference on
Volume 2, 19-22 Sept. 2005 Page(s):361 - 368
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21. **High-performance FPGA based camera architecture for range imaging**
Lepisto, N.; Thornberg, B.; O'Nils, M.;
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22. **Utilizing higher order statistics of packet interarrival times for bottleneck detection**
Varga, P.; Kun, G.;
End-to-End Monitoring Techniques and Services, 2005. Workshop on
15 May 2005 Page(s):152 - 163
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23. **View-dependent rendering of multiresolution texture-atlases**
Buchholz, H.; Dollner, J.;
Visualization, 2005. VIS 05. IEEE
23-28 Oct. 2005 Page(s):215 - 222
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24. **Fine water mist fire protection system**
McBride, W.E.;
Petroleum and Chemical Industry Conference, 2001. IEEE Industry Applications Society 48th Annual
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25. **3D Measurements in Cargo Inspection with a Gamma-Ray Linear Pushbroom Stereo System**
Zhigang Zhu; Li Zhao; Jiayan Lei;
Computer Vision and Pattern Recognition, 2005 IEEE Computer Society Conference on
Volume 3, 20-26 June 2005 Page(s):126 - 126
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